



Energy Storage for Vehicle Fast Charging  
and Grid Integration

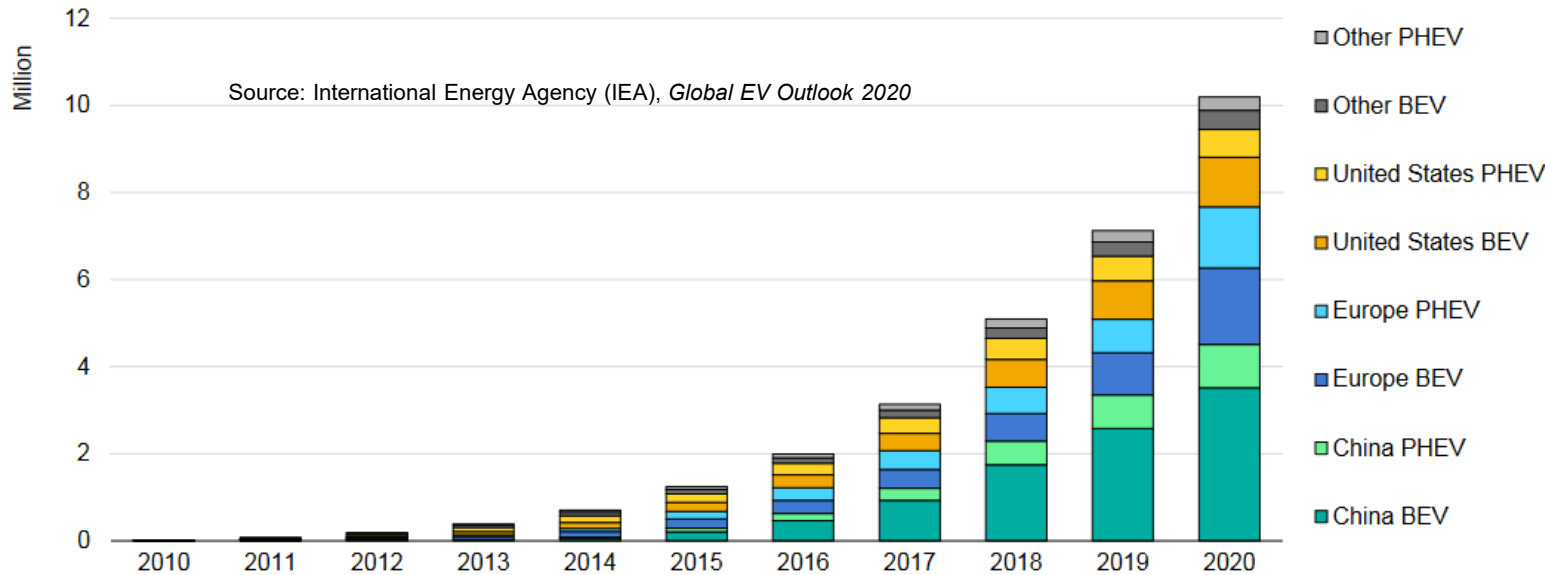
## SCIENCE BRUNCH

[www.klimafonds.gv.at](http://www.klimafonds.gv.at)



# Transition to Electric Mobility

Global electric car stock, 2010-2020

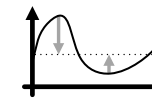


***“Publicly available EVSE outlets need to grow by a factor that ranges between 7 and 25 by 2025, amounting to between 4 million and 14 million outlets globally in 2030.”***

(International Energy Agency, „Global EV Outlook 2017“)

We all know the challenges...

1. Peak Loads



2. Charging Network



3. Volatility



4. Cost



5. Grid Stability



6. User Friendliness

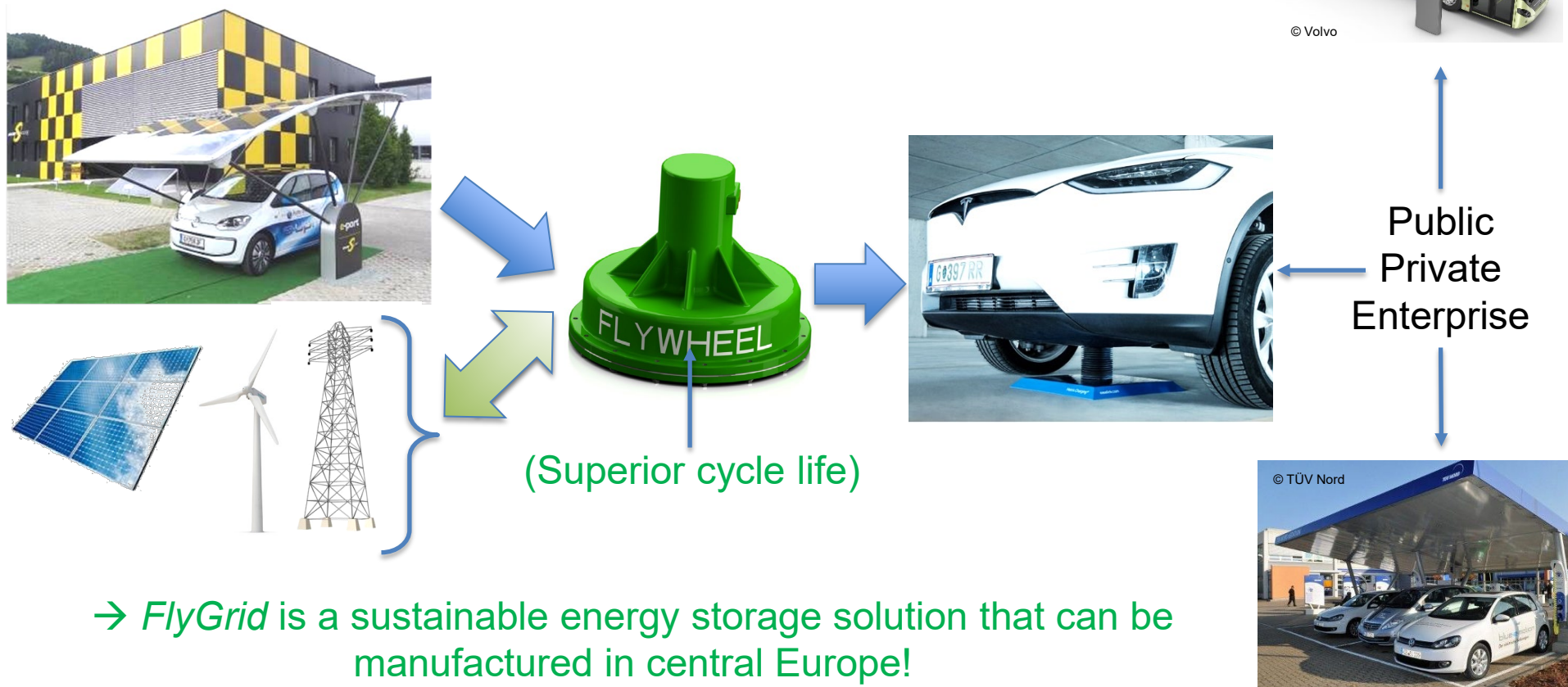




# Flywheel Energy Storage for Electric Mobility

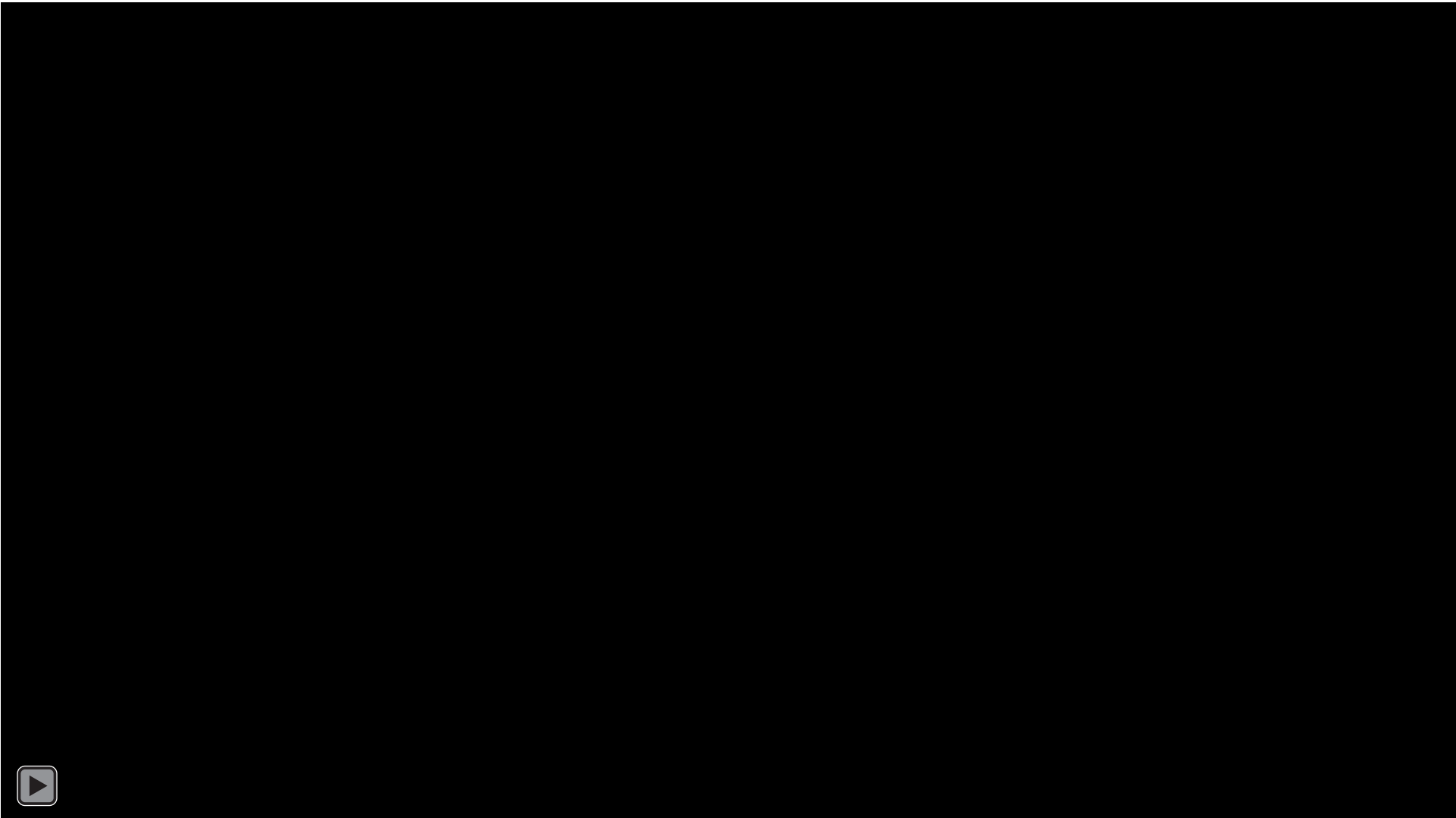
„**Peak shaving**“ for fast charging applications:

- Avoid costly modification of existing electricity grid
- Make use of local renewable sources such as wind / solar
- Increase grid stability and power quality



→ FlyGrid is a sustainable energy storage solution that can be manufactured in central Europe!

# Flywheel Energy Storage for Electric Mobility



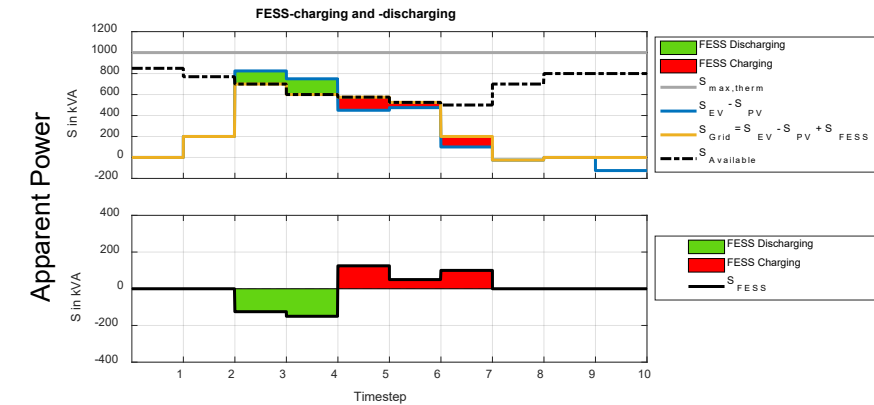
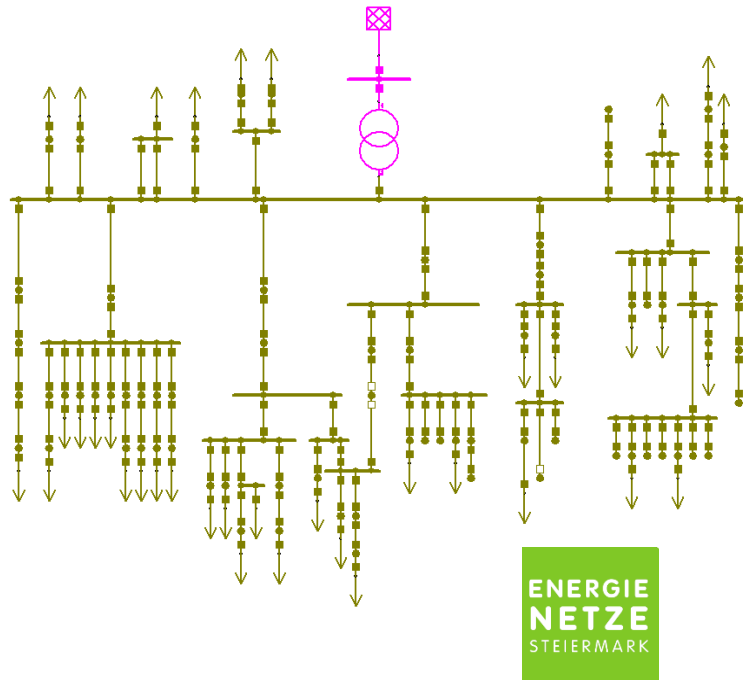
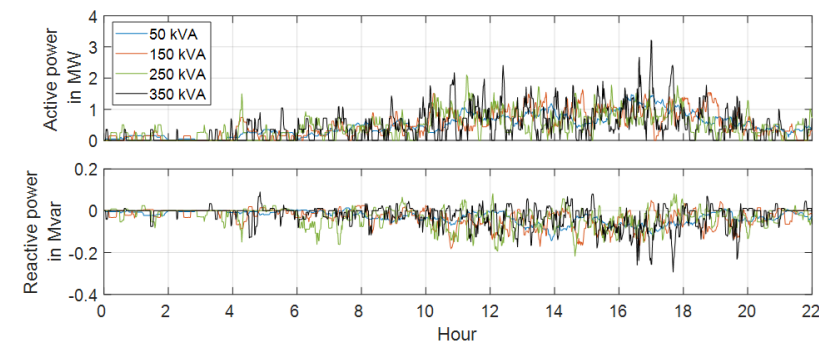


# Grid Modelling and Use-Cases

1. Modeling of time-resolved EV charging patterns

2. Identification of potential grid overloads

3. Determination of FESS target properties



EV Use Case	Charging power (kVA)
1 Charging at public parking lots	3.7 – 100.0
2 EV car sharing	3.7 – 100.0
3 Highway fast charging	50.0 – 350.0
4 Public charging at shopping centers	3.7 – 100.0
5 Electrified busses	100.0 – 600.0
6 Electrified taxis	3.7 – 100.0
7 Electrified last-mile delivery trucks	100.0 – 350.0

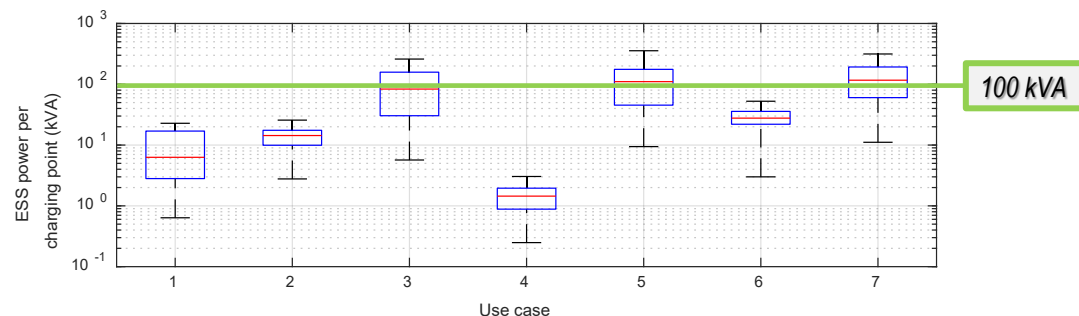
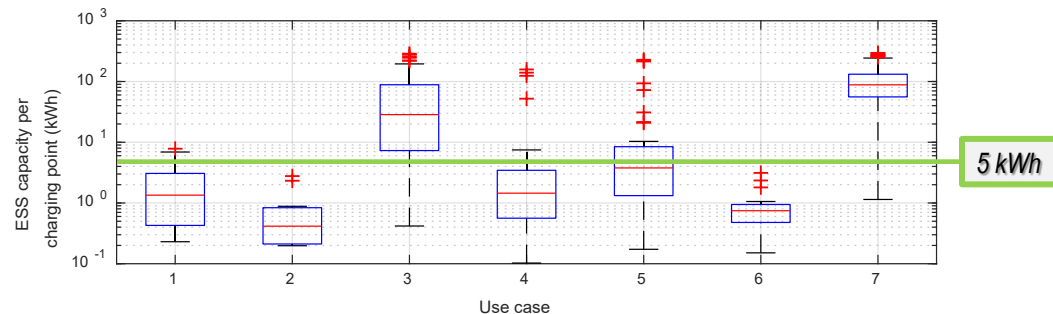
FESS parameter per module	Value
Efficiency: FESS charging	90 %
Efficiency: FESS discharging	90 %
Max. Idling losses	0.5 kW
Cos(φ): FESS charging	1.0

# Methodology to Determine FESS Properties

## FESS Target Requirements

### Research question:

*What are the desired FESS specifications in order to allow proper peak shaving in EV fast charging applications?*

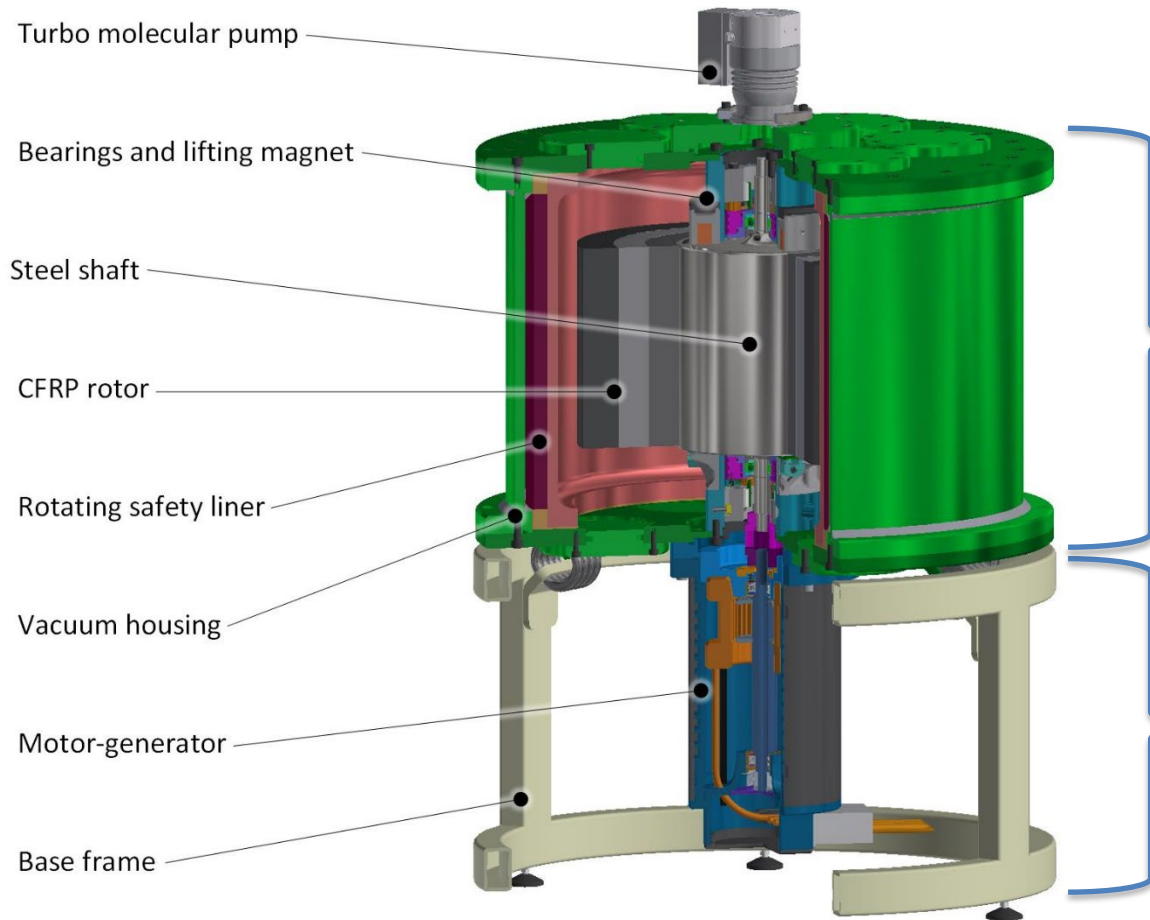


EV Use Case	
1	Charging at public parking lots
2	EV car sharing
3	Highway fast charging
4	Public charging at shopping centers
5	Electrified busses
6	Electrified taxis
7	Electrified last-mile delivery trucks

- **2/3 of the current EV applications require:**  
 $< 5 \text{ kWh}$   
 $< 100 \text{ kVA}$
- *Remaining applications can be covered by a modular expansion of FESS*
- *Not all EV applications allow grid load mitigation via FESS*



# Modular and Flexible High-Performance FESS Design

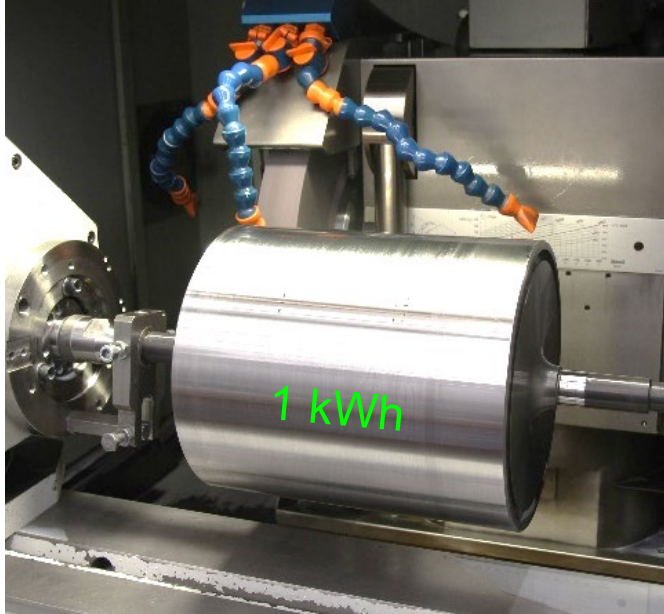


**Rotor:**  
Determines Energy  
(5 kWh)

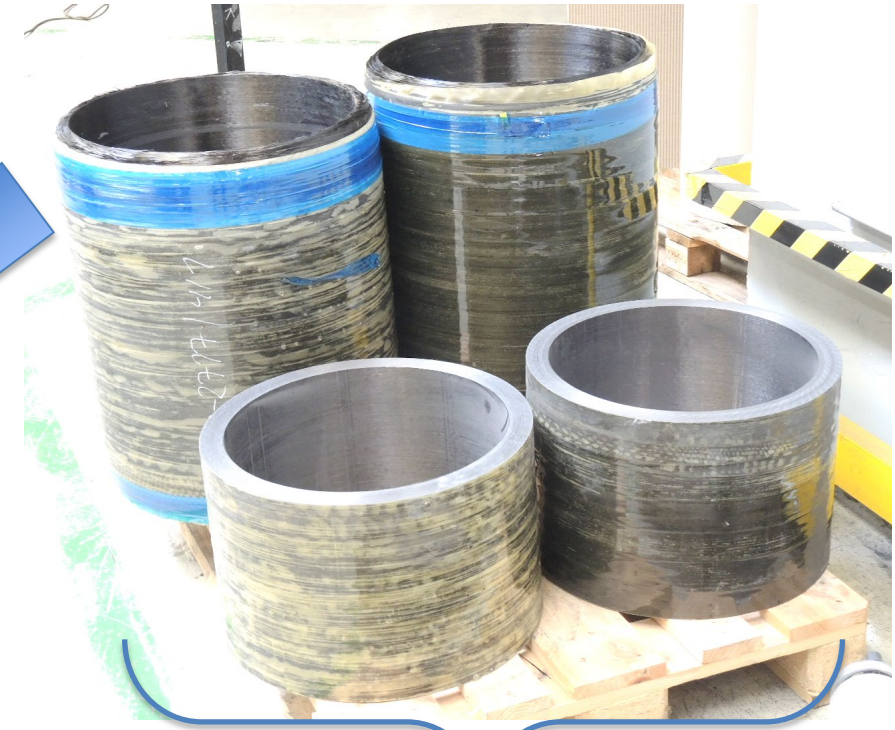
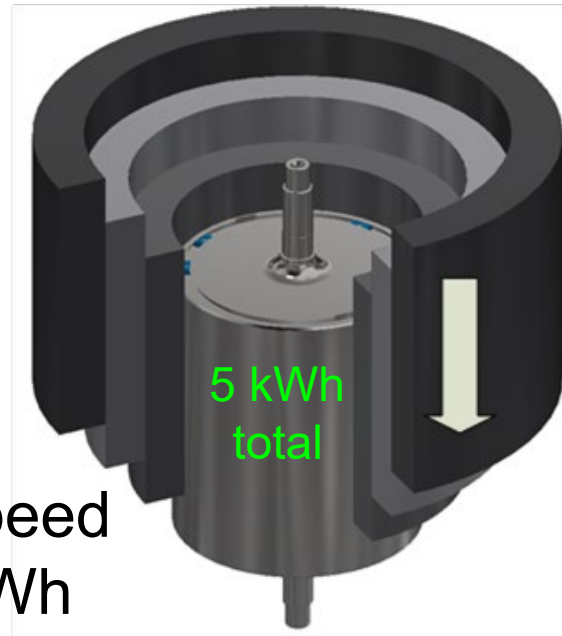
**Generator:**  
Determines Power  
(100 kW)



# High-performance CFRP Rotor



Axial press-fitting of hoops



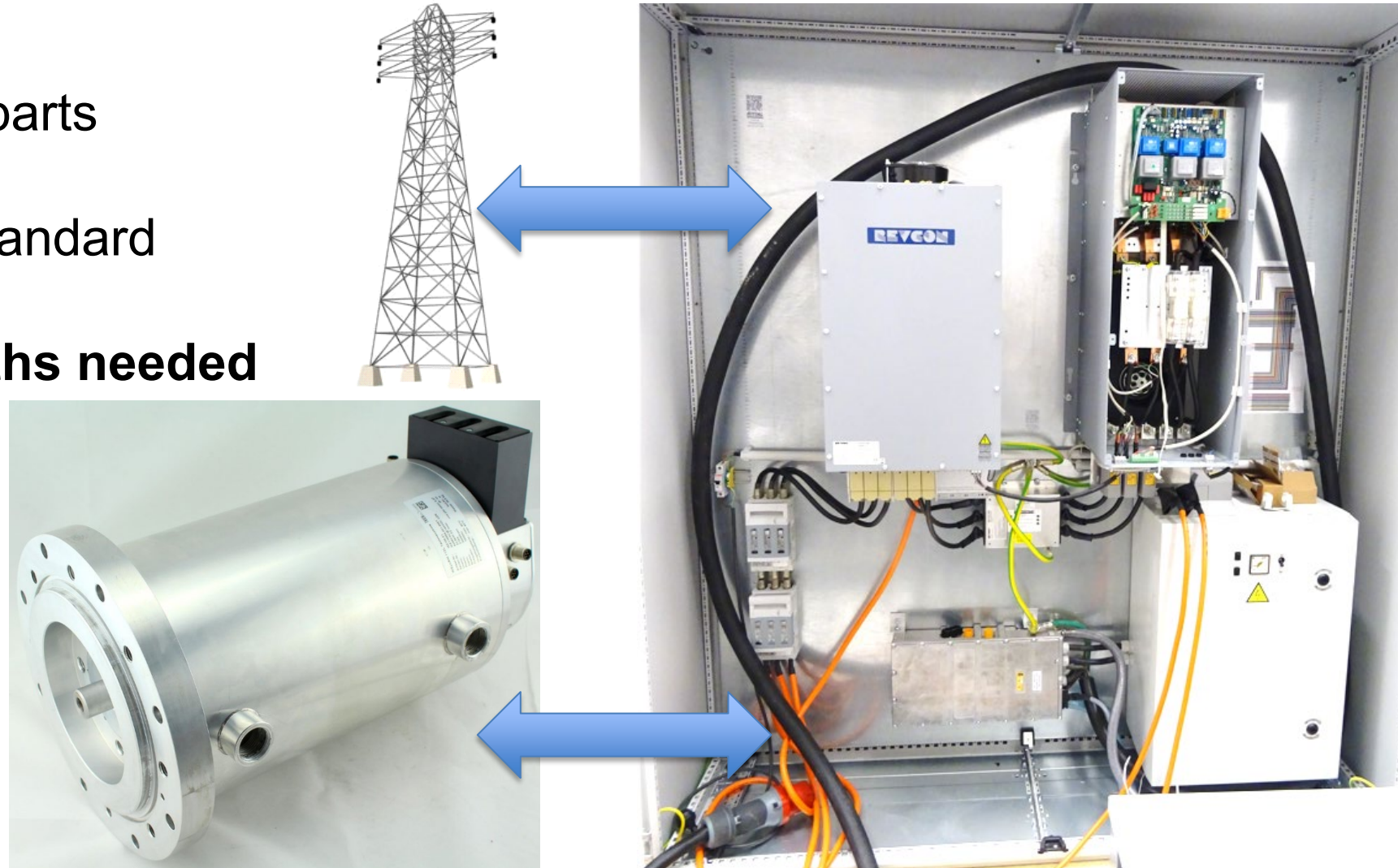
- ✓ Approx. 600 x 250 mm
- ✓ 30 000 rpm → 950 m/s rim speed
- ✓ Each rotor module offers 5 kWh

✓ Unique expertise as benefit for Austrian economy



# Power-Unit: Synchronous Reluctance Machine

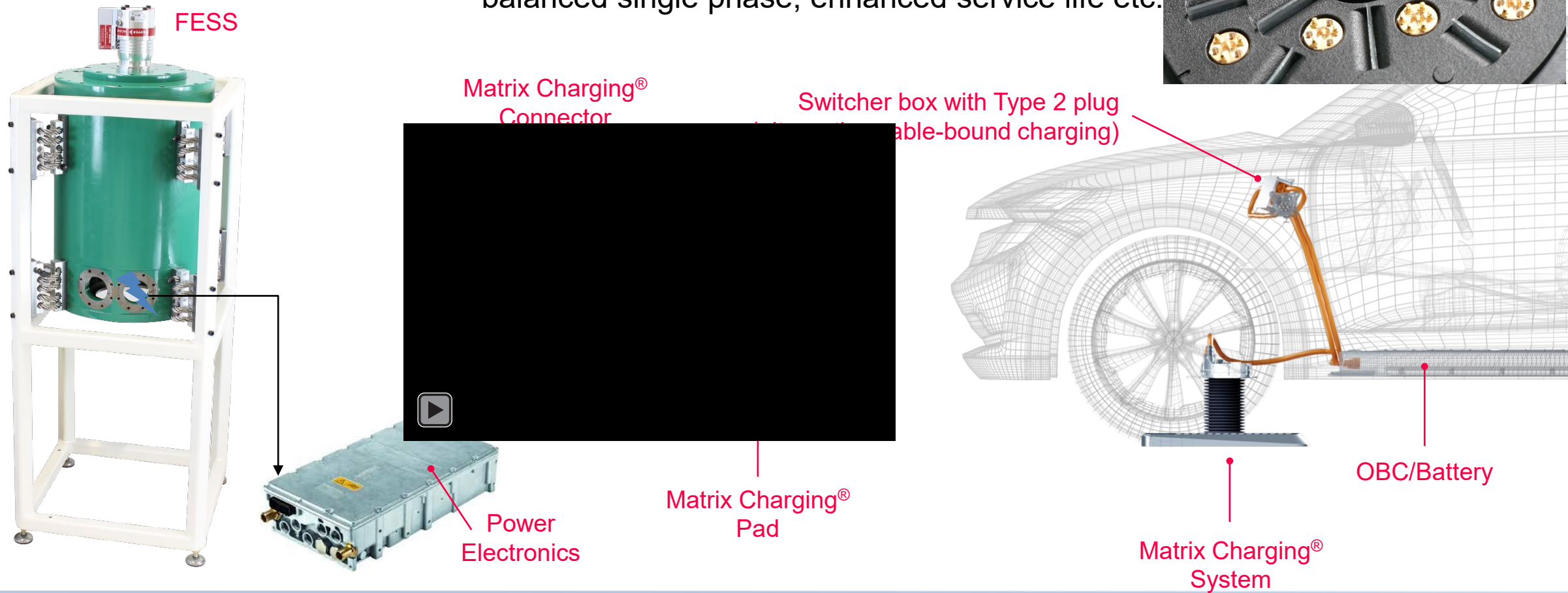
- **Low losses in rotor**  
→ No current-carrying parts (important in vacuum)
- **High efficiencies** for standard applications (IE4)
- **No magnets / rare earths needed**  
→ Easy to recycle
- **No cogging torque**  
→ Ideal for FESS with low idling losses



# Automatic Conductive Underbody Charging

## Optimization and Integration of Innovative Charge Point

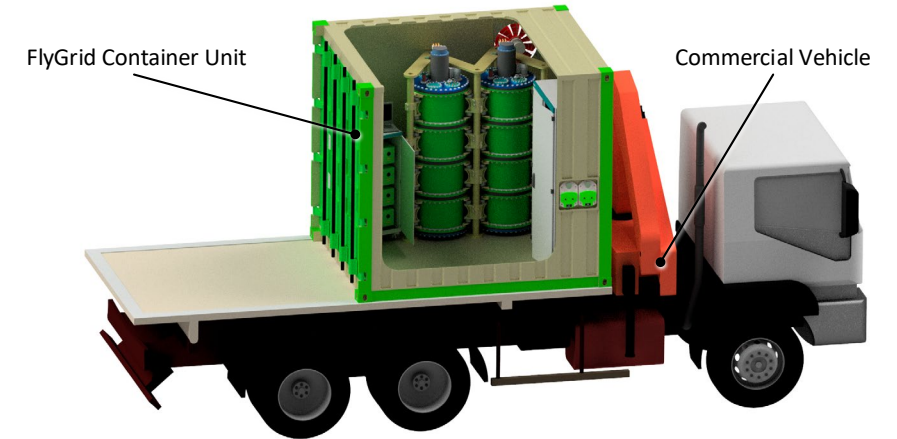
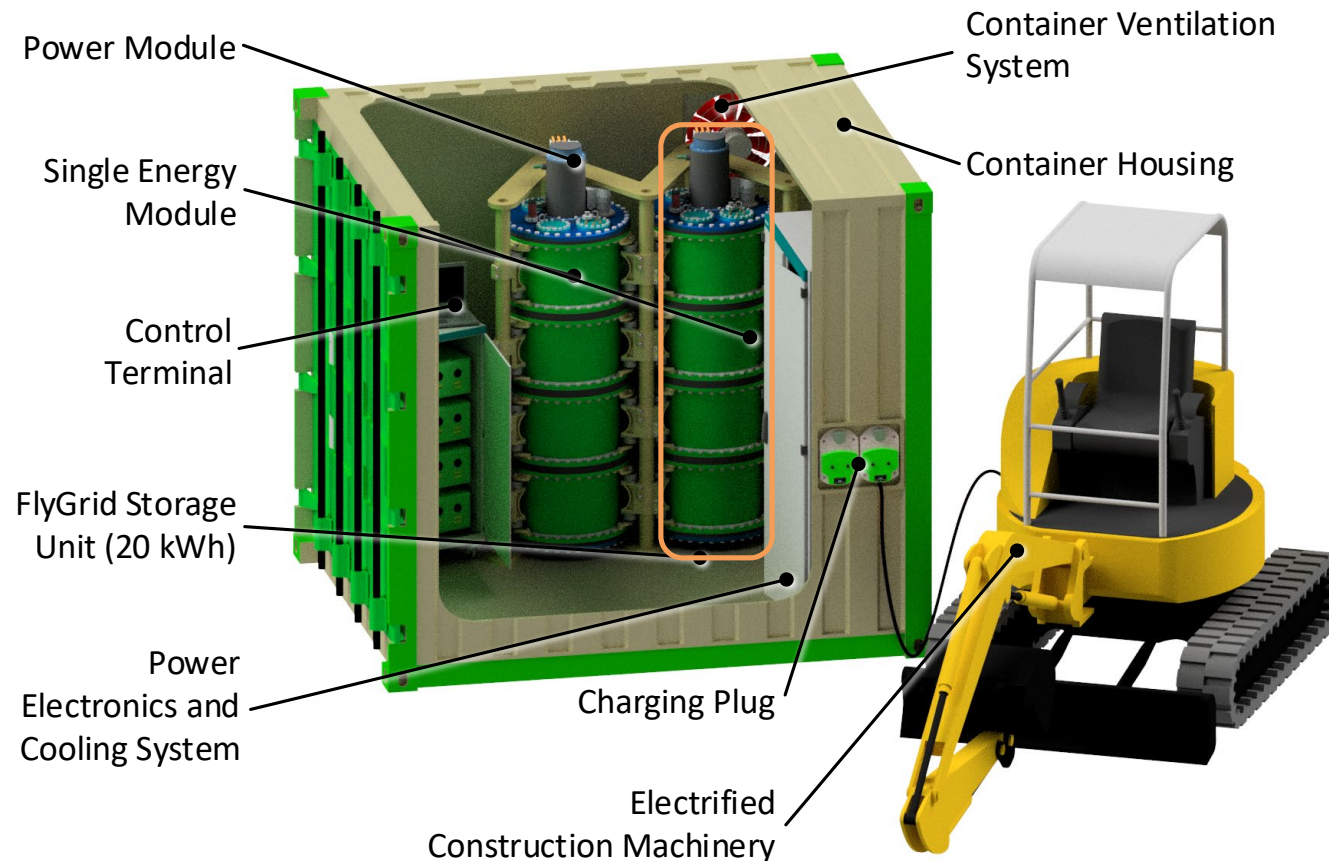
→ Improved safety, power, communication, balanced single phase, enhanced service life etc.





# Other FESS Applications

**FESS is not a hazardous good → easy transportation**



**Suitable for other applications, e.g.:**

- Grid stability, voltage control, ...



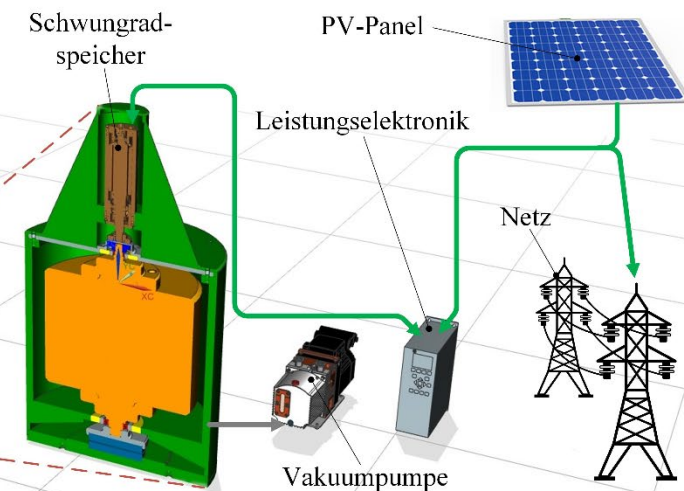
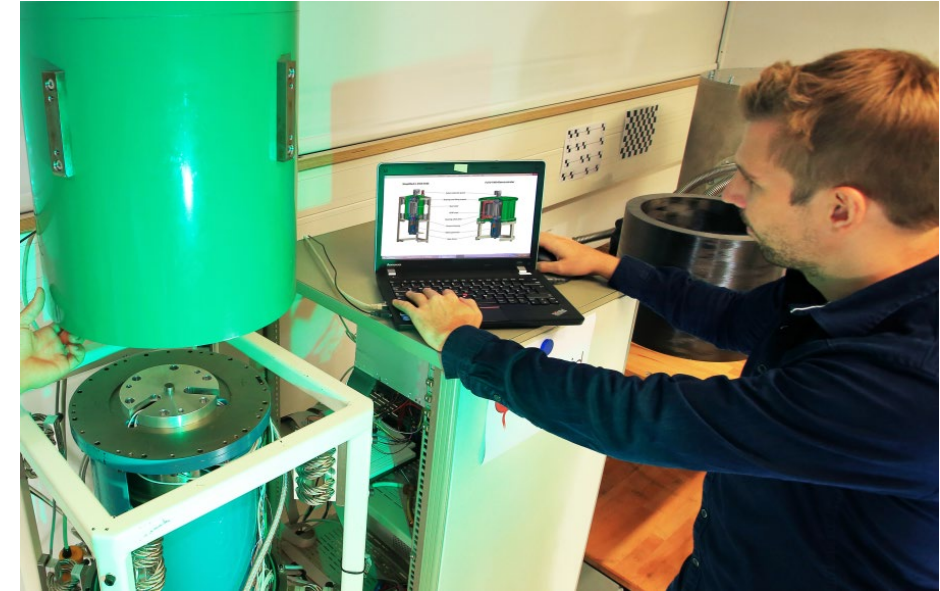
# Summary and Outlook

## Achievements so far:

- Use-cases and possible grid overloads identified
- Target properties of FESS determined
- FESS prototype built and undergoing lab testing
- Matrix Charging system developed

## Nest Steps

- Installation of Demo-Facility @ *Energie Steiermark*, Graz in fall 2022
- Commercialization and / or follow-up project planning
- Exploration of other use-cases, such as: grid stability, manufacturing companies, uninterruptable power supply etc.





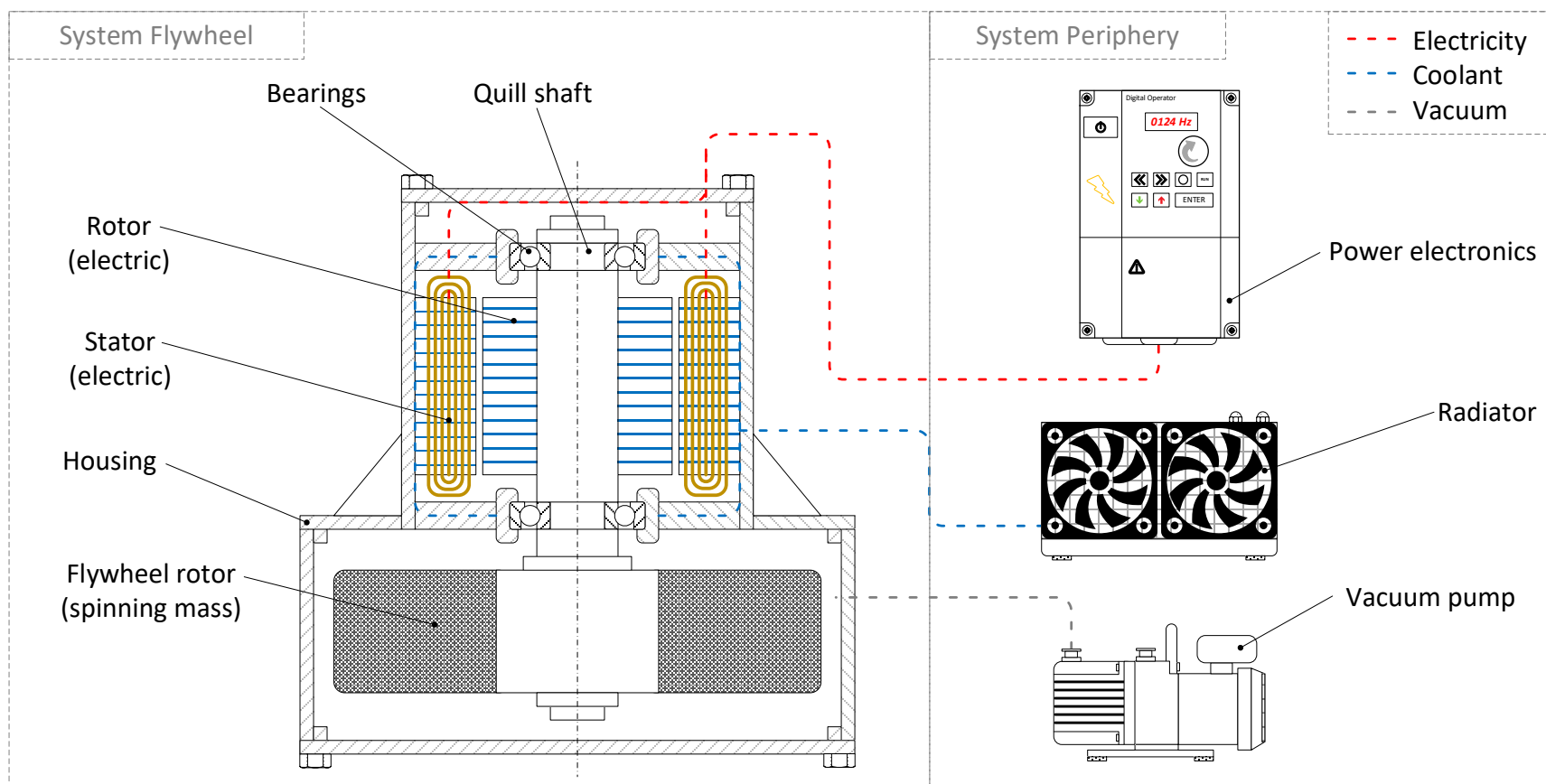
# Thank you for your attention!

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# The *Electromechanical* FESS



## Physical Advantages

- ✓ High power density
- ✓ Very high cycle life
- ✓ Uncritical deep discharge
- ✓ Precise SoC determination
- ✓ No capacity fade over time

## Further Advantages

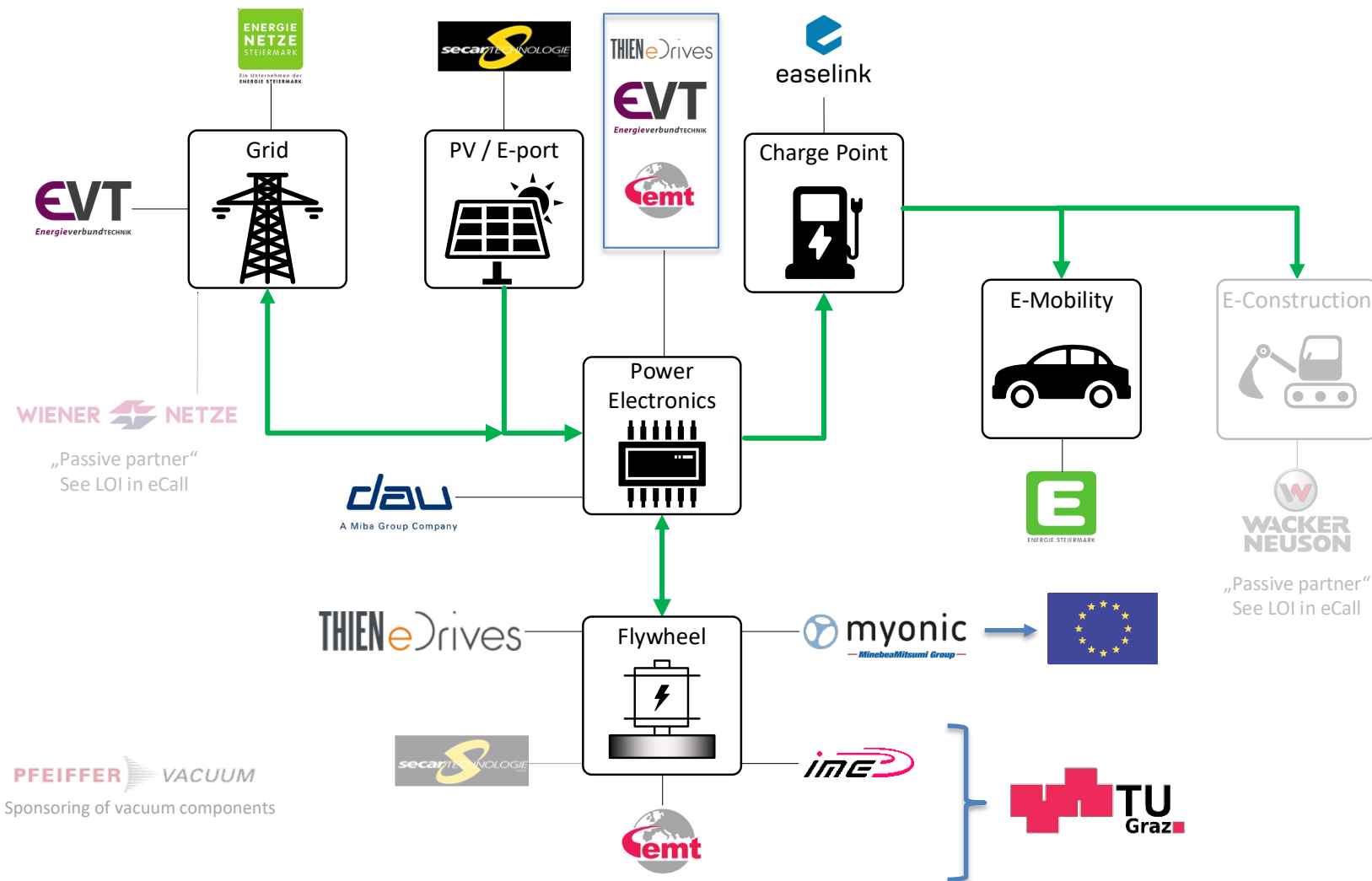
- ✓ High potential energy density
- ✓ Potential for low cost design
- ✓ Good recyclability
- ✓ Operation under low/elevated temperatures
- ✓ Manufacturing in AUT/ EU

## Current Challenges

- Self-discharge
- Low energy density
- Manufacturing cost



# Consortium



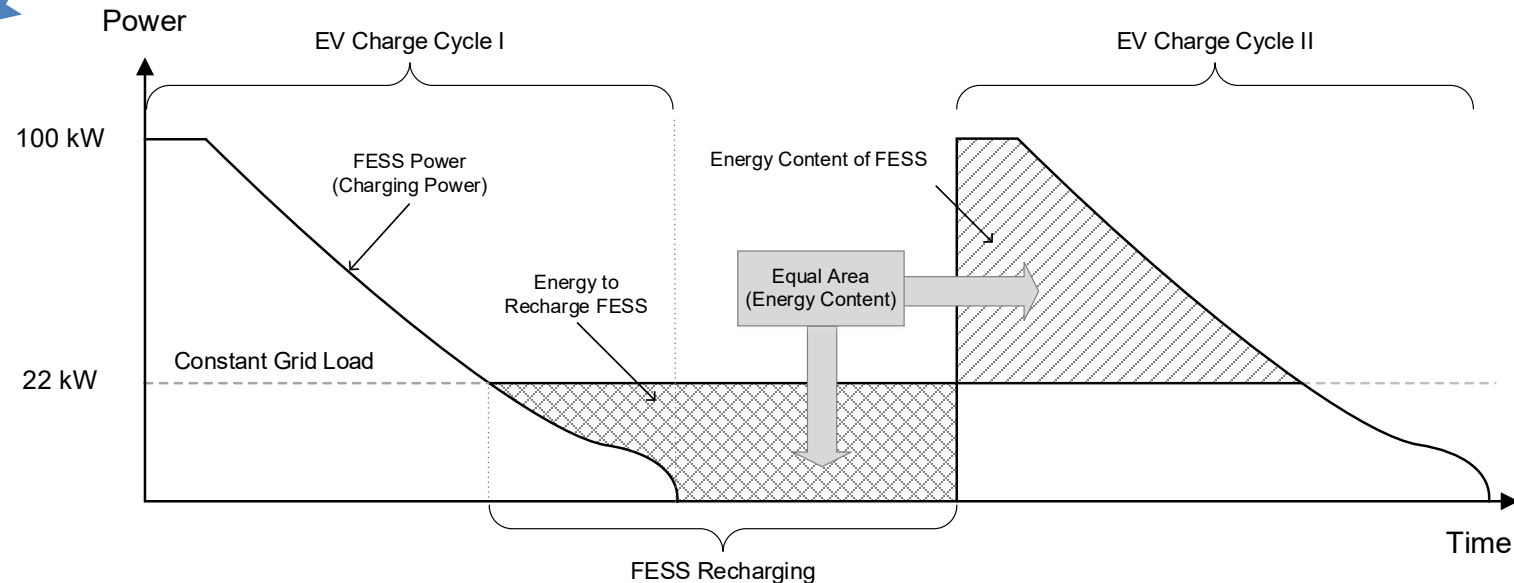
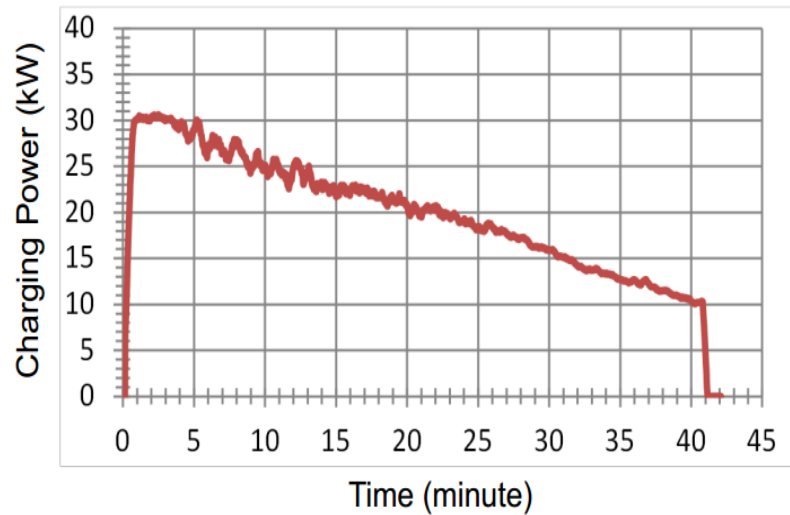
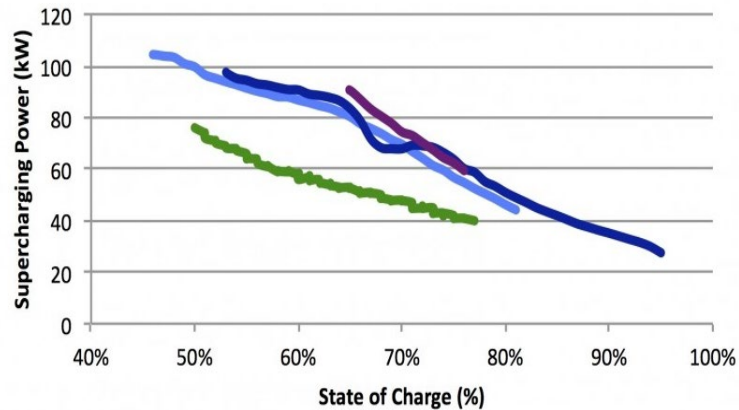
# Flywheel Energy Storage for EV Charging Stations

16

## Implementation of FESS

Buffer energy storage with limited energy content?

Charging power over time for *Tesla Model S* (top) and *Nissan Leaf* (bottom).





# Energy Storage Options

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## Chemical Battery vs. Flywheel

### Li-Ion Battery (*Tesvolt TS HV 70*)

- Roundtrip efficiency < 94 %
- 76 kWh
- 75 kW (1C), 4C short term
- 6,000 cycles (1C, 70% EoL, 100 % DoD)
- 30 years
- ~ 550 €/kWh
- **LCOS → 0.10 €/kWh**
- 860 kg



[www.tesvolt.com](http://www.tesvolt.com)

### Flywheel (*Chakratec KPB*)

- Roundtrip efficiency < 90 %\*
- 10 x 3 kWh
- 100 kW (50 kW nominal)
- 20 years / > 200,000 cycles
- ~ 2500 €/kWh
- **LCOS → 0.015 €/kWh**
- 10,000 kg



[www.chakratec.com](http://www.chakratec.com)

\* No manufacturer data available. Value taken from [www.stornetic.com](http://www.stornetic.com)

# FESS History and Strategic Project Goals

## Why develop a new FESS?

a. Chr. - 1550



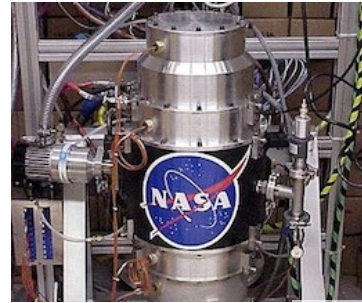
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2020



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Technological advantages and potential compared to batteries



Goal is an improvements beyond state of the art and cost reduction



Sustainable energy storage will play a major role also in other sectors

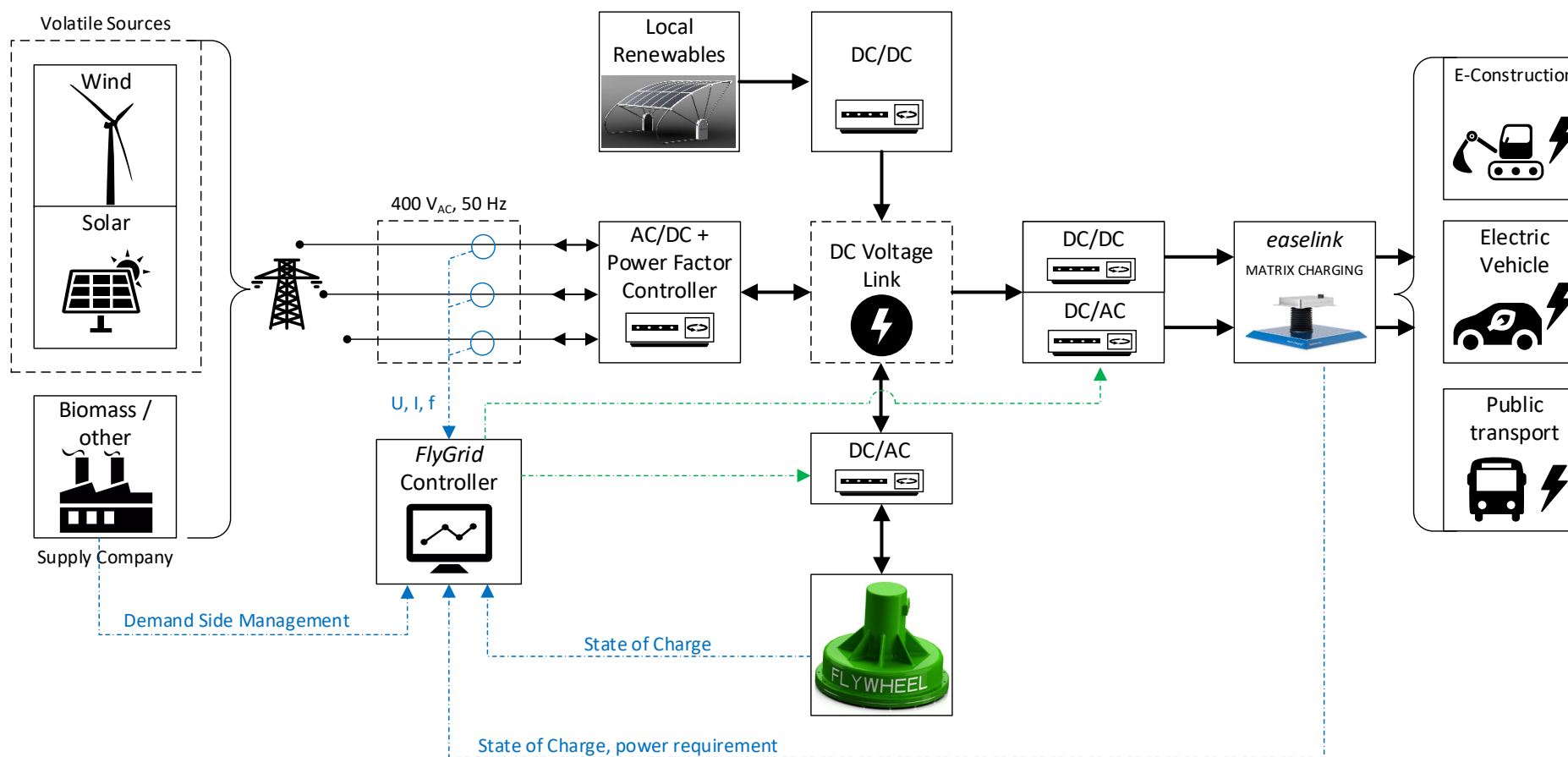


*FlyGrid* does not only develop the FESS, but has a bigger scope



Bringing technology and know-how to Austria

# Implementation of FESS





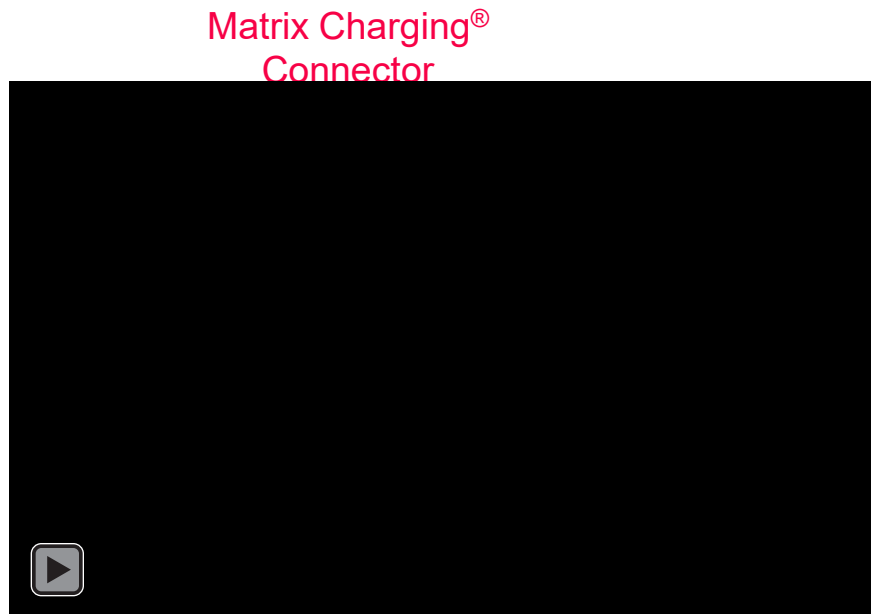
# Key facts of 4<sup>th</sup> project year

- **Project ready to enter the final phase** without any major drawbacks
- Integration of new partner FWT composites and rolls successful → catching up on previous delay of **Task 5.1** (rotor manufacturing)
- A small-scale 1-kWh flywheel energy storage unit was built and is undergoing lab-testing at system level
- **Major progress in WPs 5, 6, 7** achieved according to plan.
- **Some minor delays** due to **supply chain issues**.
- Successful completion of the **Half-Time Symposium** within the framework of the *A3PS Ecomobility Symposium*.
- The final steps for the **roll out of the demonstrator facility** planned.



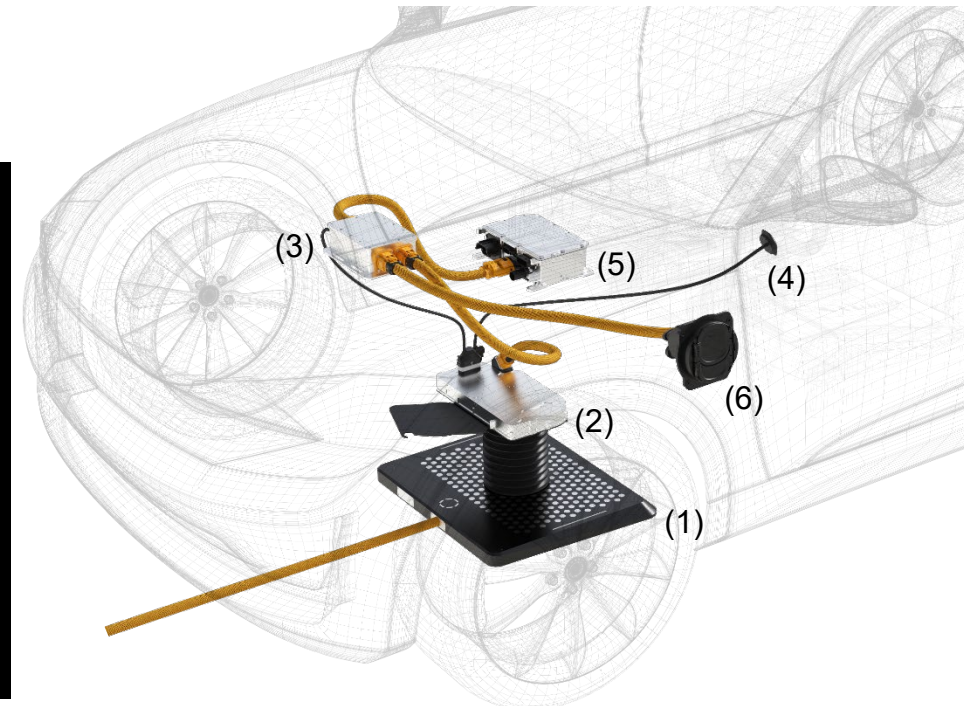
# WP7: Power Electronics, Controls and Charge Point Interface Development

## Task 7.3: Optimization and Integration of Innovative Charge Point



Matrix Charging®  
Connector

Matrix Charging®  
Pad



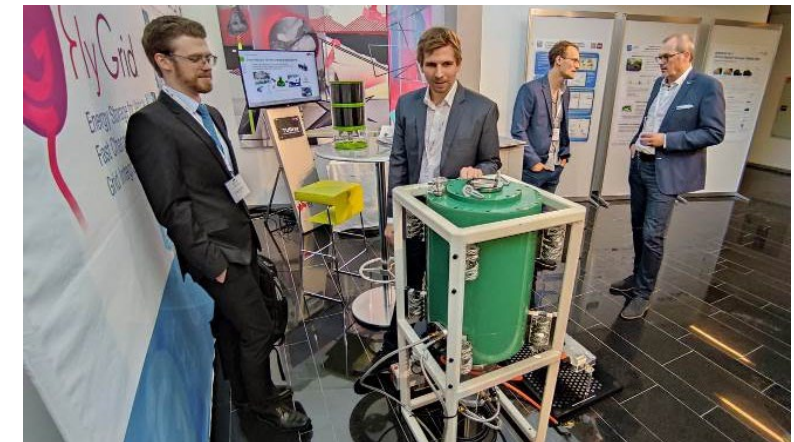
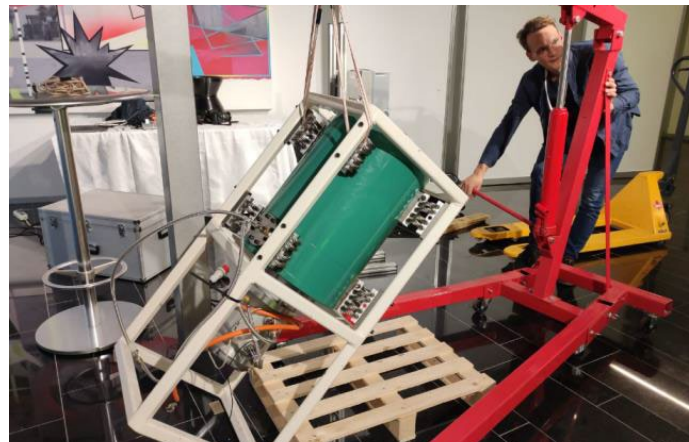
- (1) Matrix Charging® Pad
- (2) Matrix Charging® Connector
- (3) Switch box
- (4) User interface
- (5) Onboard charger
- (6) Type 2 inlet



# Dissemination

## Show-casing various technologies:

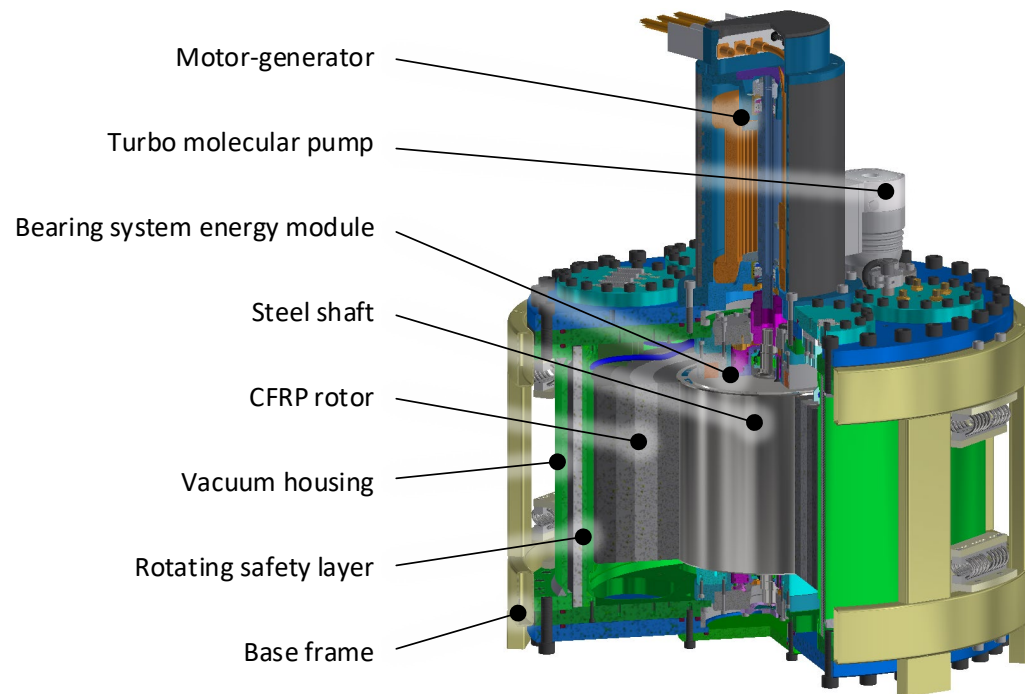
- *TeD Motor-Generator*
- *Flywheel System*
- *New Generation Matrix Charging*
- *FWT CFRP Rotor*
- *Bearing technology*
- *Small-scale demonstrators*





# WP4: FlyGrid Energy Storage

## Full scale 5 kWh FESS (Demonstration unit)



- ✓ Based on target properties (WP3/4)
- ✓ Suitable for many industrial applications

## Down-scaled 1 kWh FESS (Delay mitigation measure)



- ✓ Ready to demonstrate full functionality
- ✓ Important tool for R&D and project itself

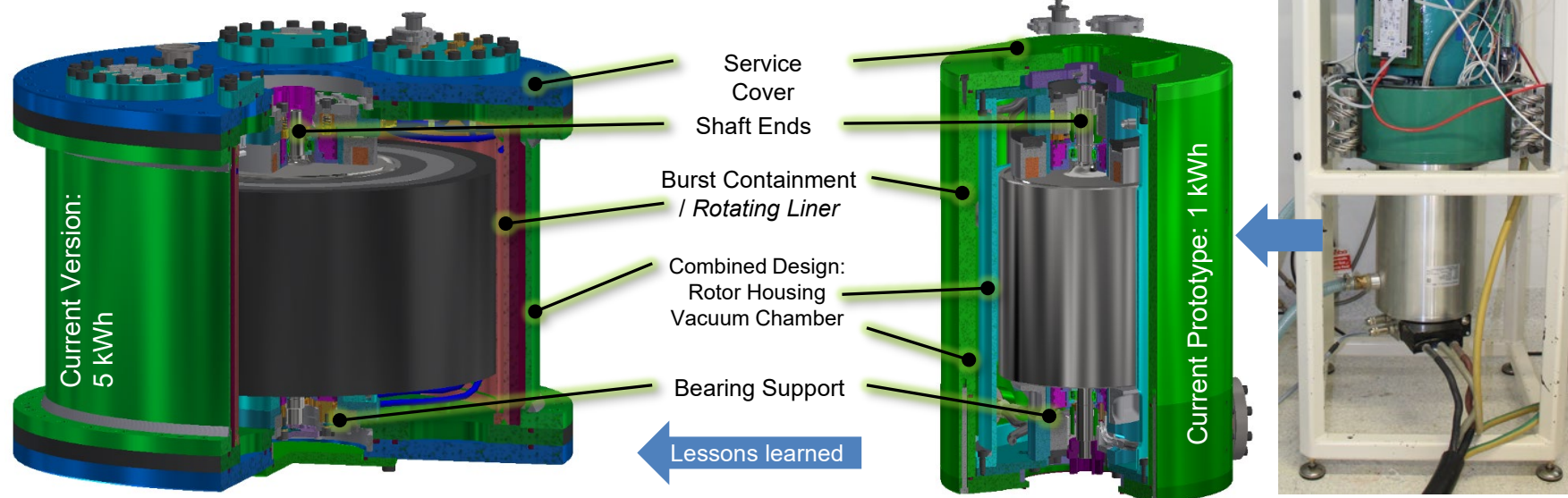
# Task 6.2.: Housing Design

## Design Optimization & Adjustments → Based on „Lessons learned“ from the current Prototype

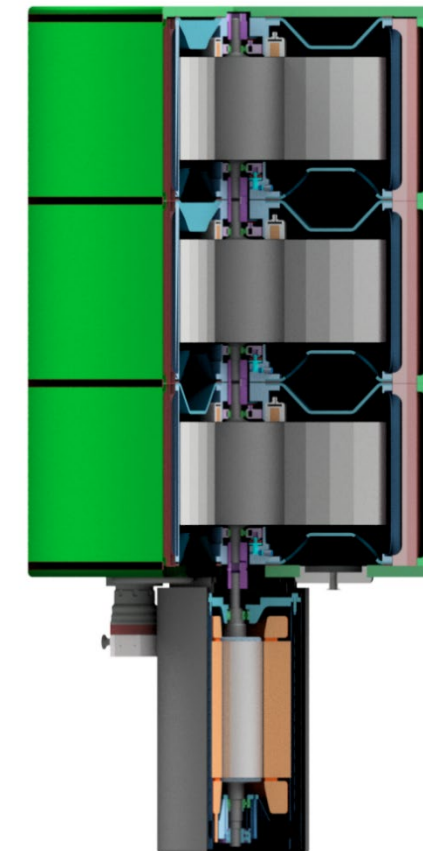
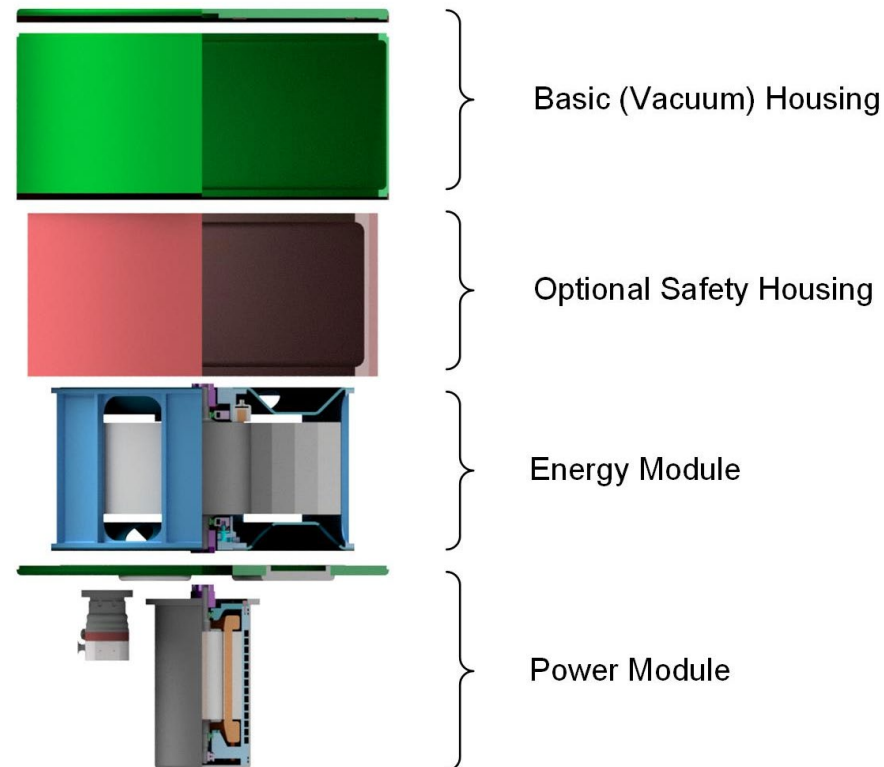
- New sensor arrangement
- Space-optimized mechanical components
- Redesign of the *Rotating Liner* & the CFRP rings
- Modified cover design

Leads to

- Shorter fail-safe shaft ends
- Equally safe more compact housing design
- Weight savings
- Improved accessibility



# FESS Modular System Design



High Power Single Unit:  
 300 kW  
 15 kWh

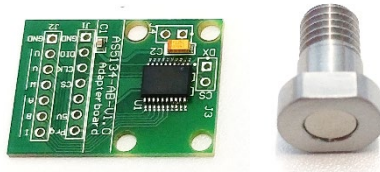


# Sensor Overview

## Adapted Commercial Sensors

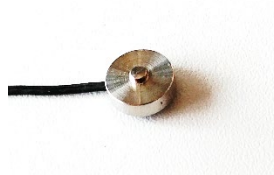
### • Magnetic Rotational Encoder

- Magnet in axle
- Measures speed and angular rotor position



### • Force Sensors

- In the bearing shields
- Measure bearing load



### • Pyrometers

- Inner bearing ring temperature
- (later also CFRP ring temperatures)



### • PT1000

- Small 2.5 mm sensor
- Outer bearing ring temperature
- Magnet temperature



## Sensors custom built by TUG (EMS)

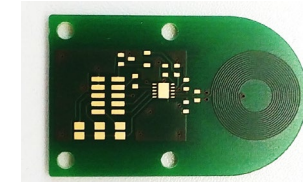
### • 3-Axis MEMS Accelerometer

- Eval. board tested on shaker
- Custom 3-axis PCB



### • Inductive Distance Sensors

- Custom PCB for inductive sensor system



### • CFRP-Rotor Strain/Deformation Measurement

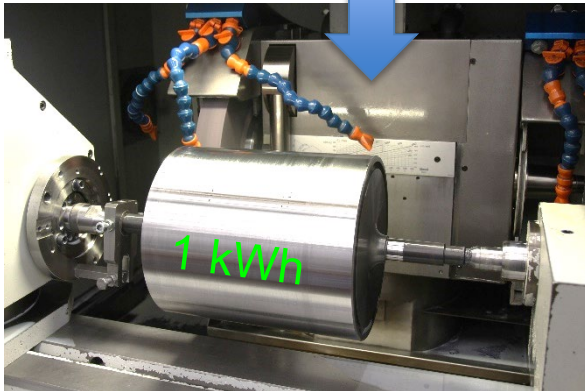
- Paint Adhesion Verification
- A painted pattern has to be applied to the rotor for contactless, optical strain/deformation measurement
- Samples of painted CFRP are accelerated in a burst enclosure



# FESS Rotor – Outlook

✓ Wet-wound CFRP hoop capabilities by FWT

✓ Steel rotor ordered

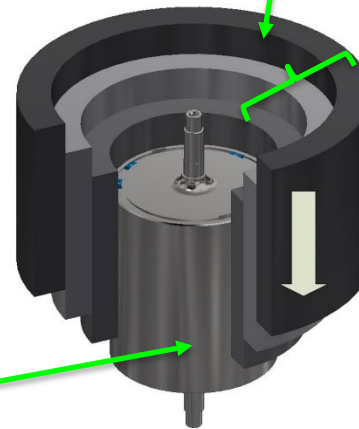


Steel shaft #2 (currently being manufactured @ Fleischer / TUG)

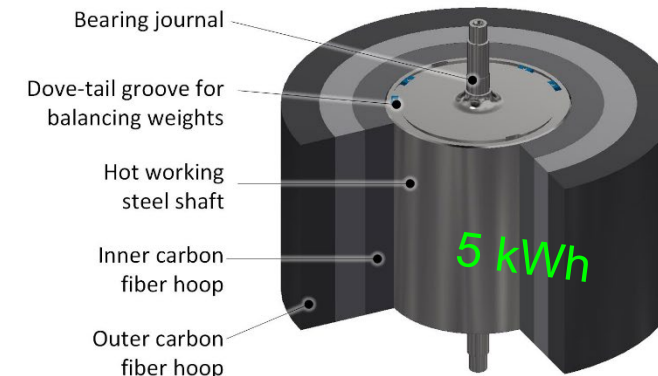
→ Base for Multiring-Composite-rotor



Outlook of manufacturing capability of FWT

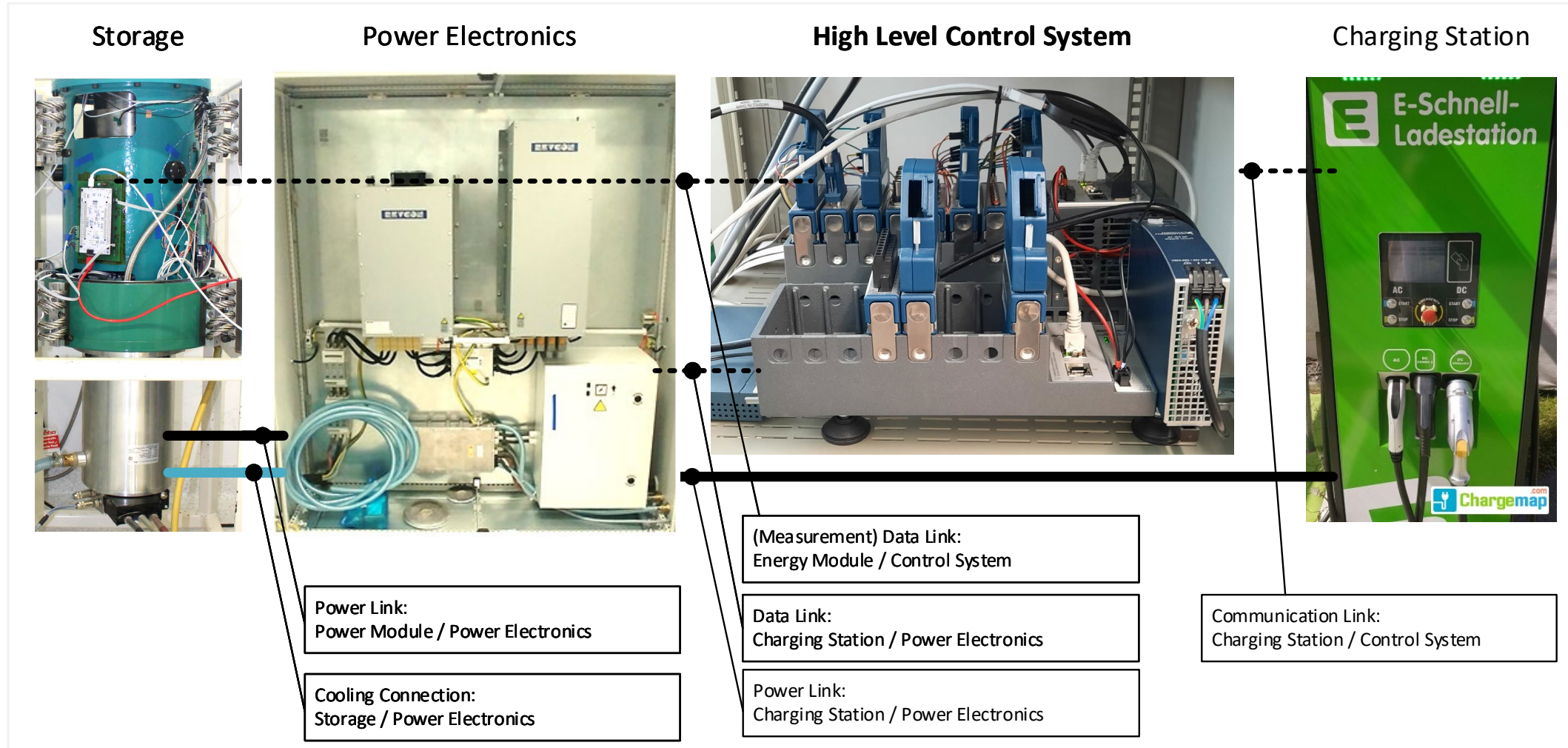


Axial press-fitting



Final multiring rotor

# T7.1b: High Level Control System



✓ **High level communication between the charging point, the FlyGrid System and the grid**

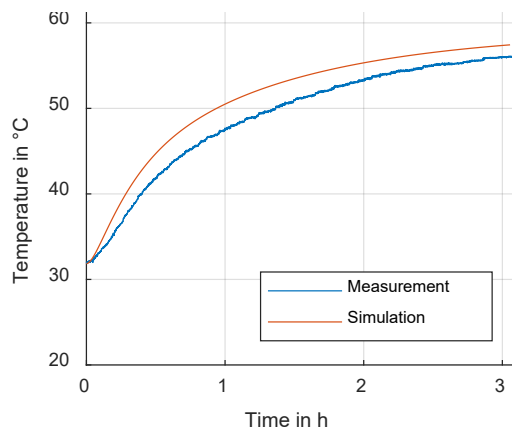


# WP8: System Verification in Lab Environment

- Successful competition of first full-speed test runs
- Overall FlyGrid power loss during run-out
- Stationary temperature determination at constant speed

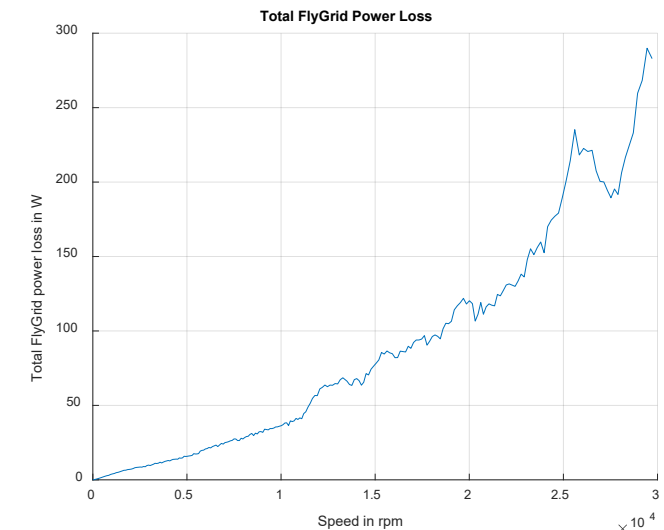


**Coupling temperature over time at 20,000 rpm**



**Steady state coupling temperature**

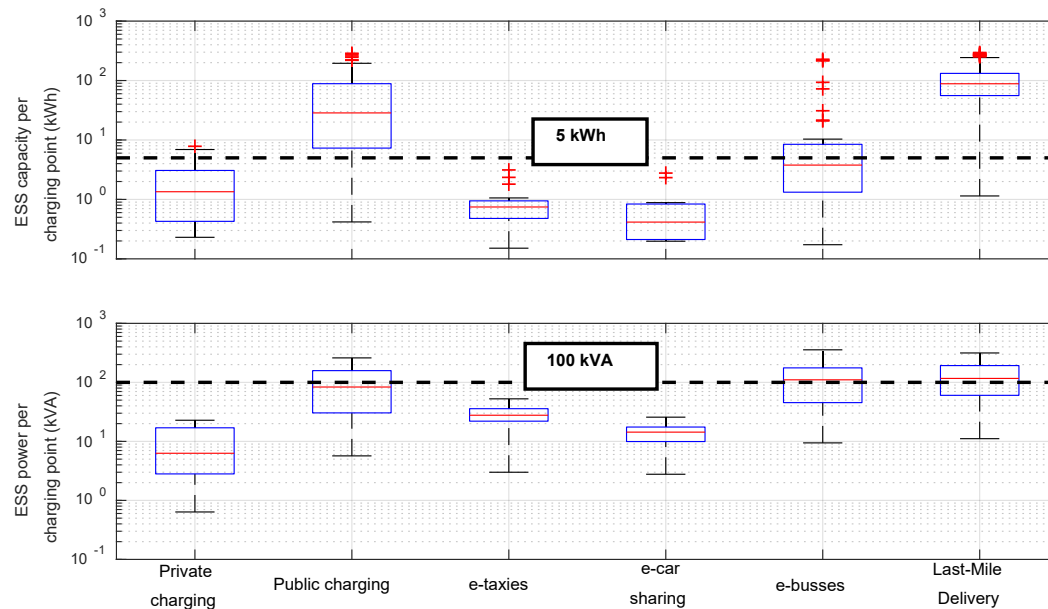
Idle speed	Coupling temperature
10,000 rpm	50.5 °C
20,000 rpm	57.8 °C
Rotor start temperature of 32 °C due to previous long term FESS testing.	



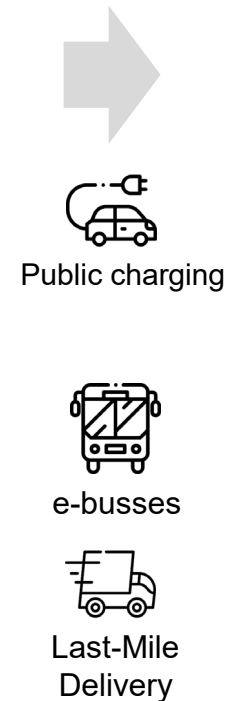
# 3. Analysis of potential grid-relieving measures

Design of energy storage systems for supplying various use cases

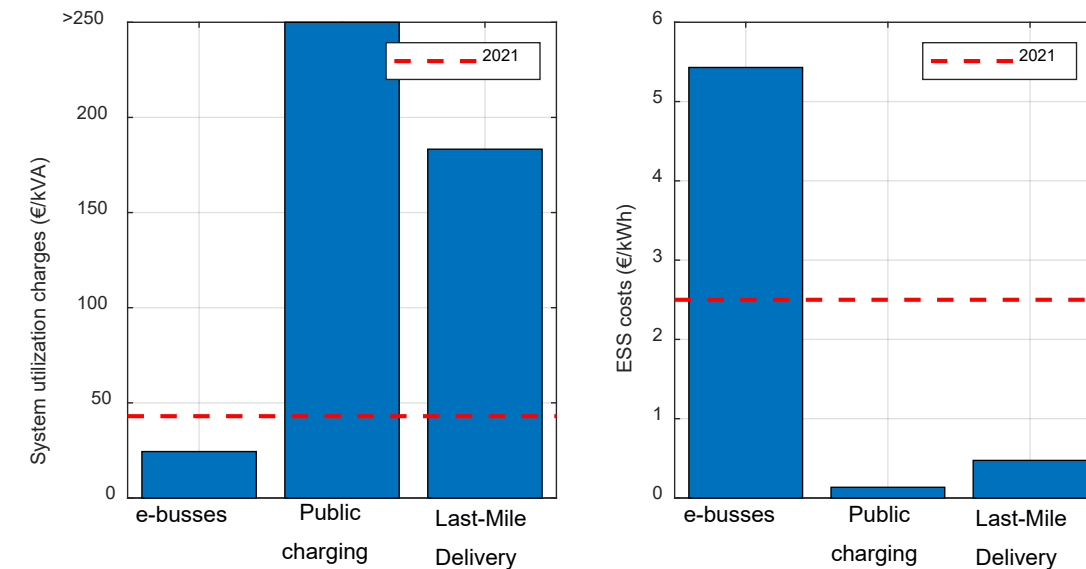
## Grid Loads and EV Charging



Even energy storages with low capacity units allow significant grid relief



Techno-economic assessment:  
How can energy storages provide cost benefits compared to classic grid reinforcements?

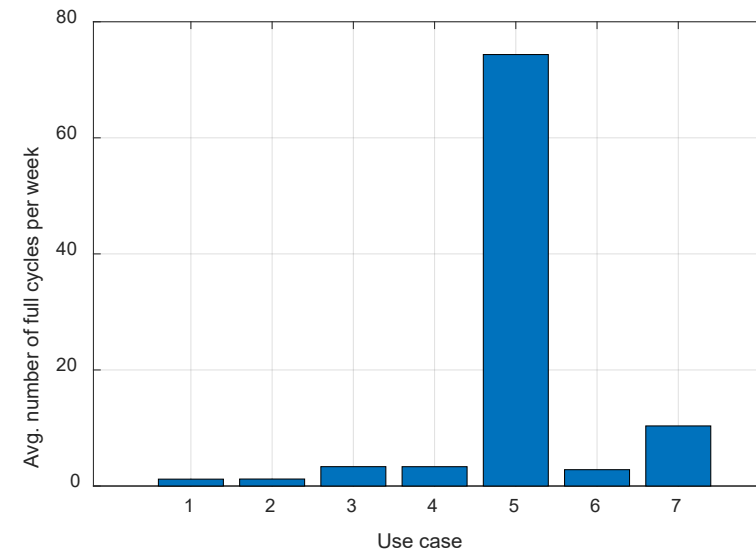
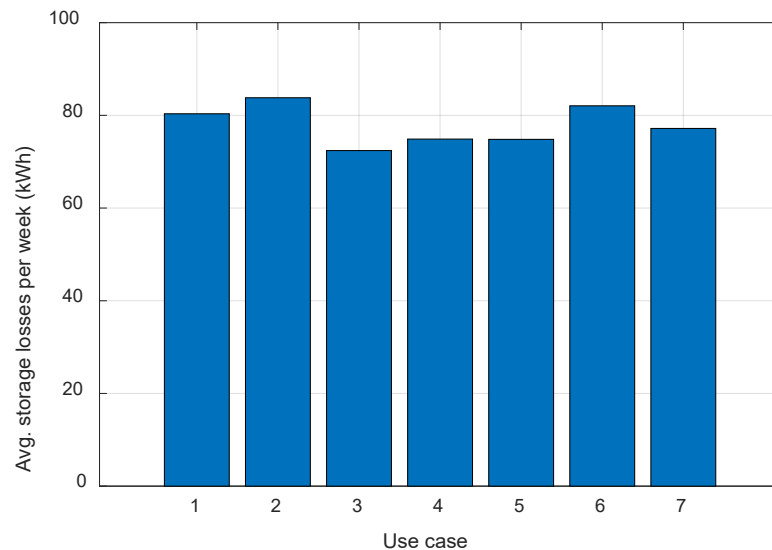


Electric busses already allow for an optimal and cost-efficient operation of energy storages

# Methodology to Determine FESS Properties

Suitability of the investigated use-cases for FESS application:

- **Battery electric busses** and fast charging at **shopping centers or highway stations** allow **lowest FESS idling losses** during operation due to high level of utilization
- **Battery electric busses** require **highest number of daily charge/discharge cycles** resulting in optimal exploitation of the FESS's specific properties



EV Use Case	
1	Charging at public parking lots
2	EV car sharing
3	Highway fast charging
4	Public charging at shopping centers
5	Electrified busses
6	Electrified taxis
7	Electrified last-mile delivery trucks



# Intermediate Summary: FlyGrid Grid Simulation Part

## Conclusions

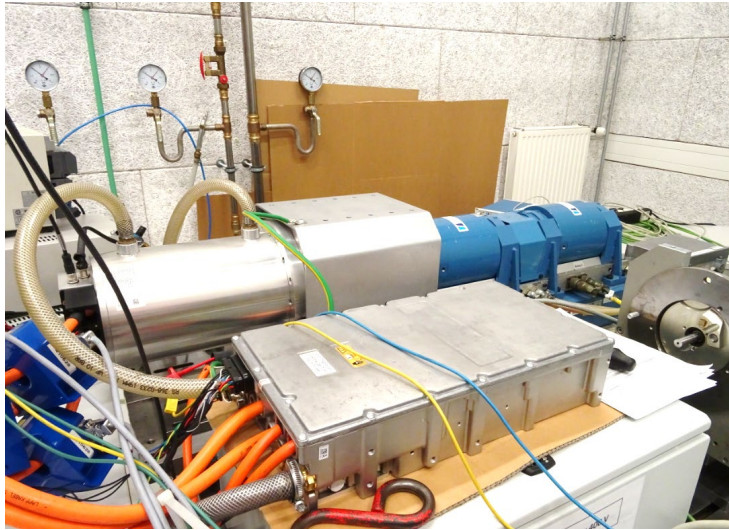
- Peak-load shaving by ESS allow grid-friendly integration of future e-mobility into present-day power grids
- Required ESS specifications strongly depend on the considered EV use case and charging power
- The majority of future charging demands can be supplied by small ESSs (e.g., 5kWh and 100 kVA)
- Electric busses represent optimum application of flywheel ESS due to frequent and constant energy demands and high charging power

## Outlook

- Combination with other flexibility options
- (Cost-)comparison with classic grid reinforcement measures



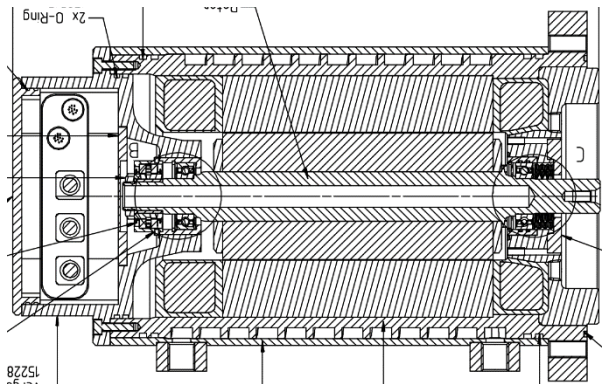
# WP 7: Testing of Motor/Generator-System



Due to the tests with test motor 2 the winding design with maximum torque per ampere and full field weakening functions was chosen.

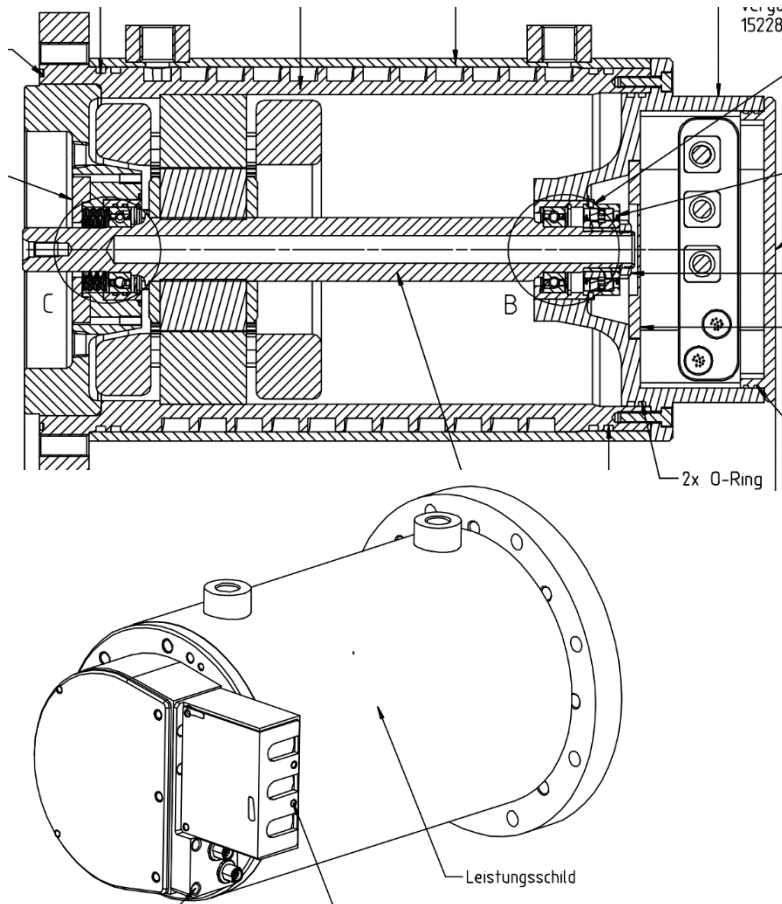
The demonstrator is running in the test-field at THIEN eDrives with semicron-inverter.

The basic and in the beginning foreseen Ld-/Lq-control strategy can be used, which is the less complicated and therefore the fastest possibility to control the motor.

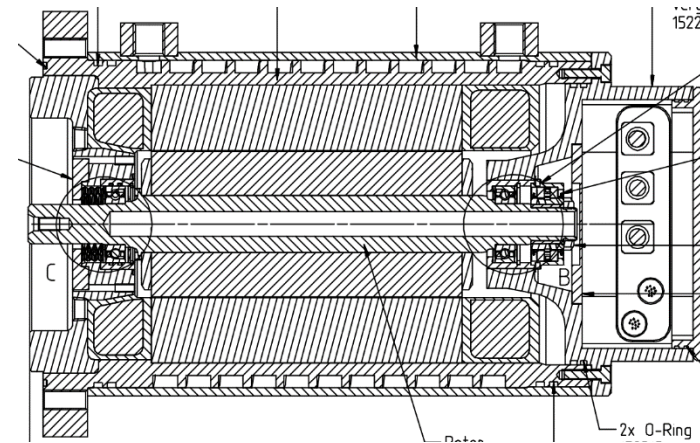


# WP4: Motor-/Generator Design

Test Motor 2

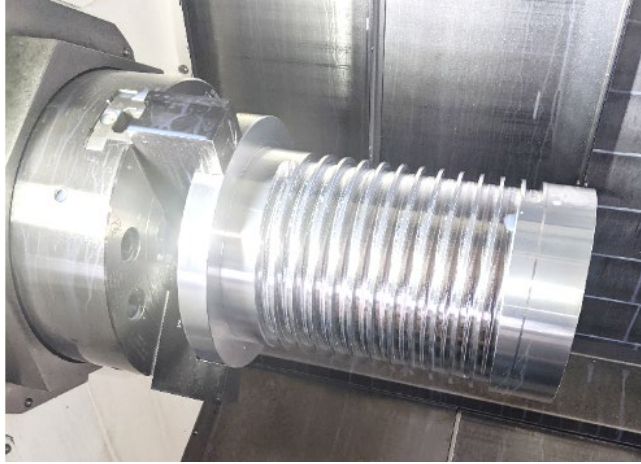


Demonstrator





## WP 5: Manufacturing of Motor/generator

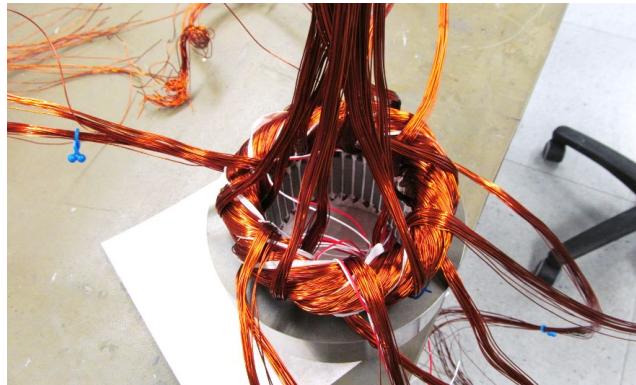


Housing production

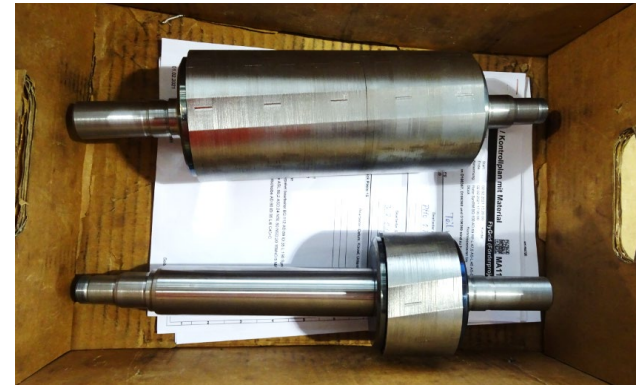


End-shield

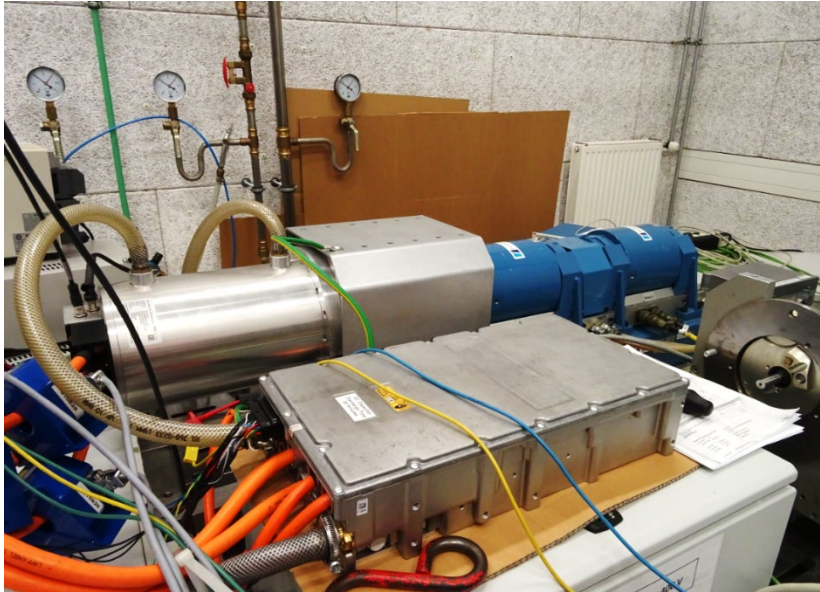
Stator of test motor with  $z_n=6$



rotors of test-motor and demonstrator



## WP 5: Testing of Motor/Generator (updated comp. to intermediate report Nr 3)



Test motor 2 is running in test-field at TeD with *Semicron*-inverter.

Foreseen control strategy for high dynamic control is implemented, which is based on differential  $L_d/L_q$ -parameters

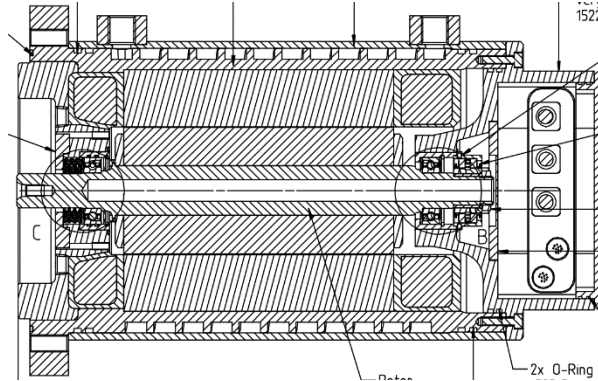
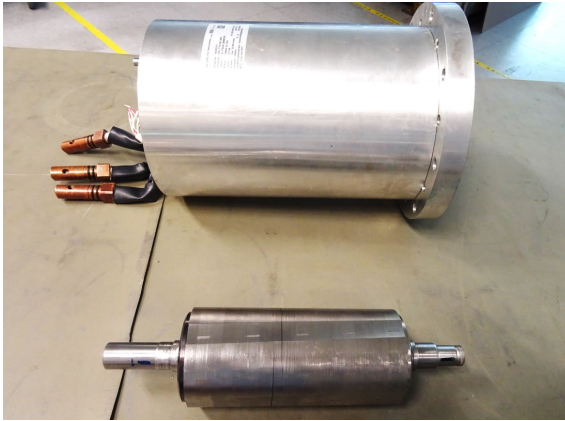
Control parameters are working properly; point of best torque per ampere like predicted

**Differences in predicted torque consumption:** 200 A measured instead of 160 A calculated

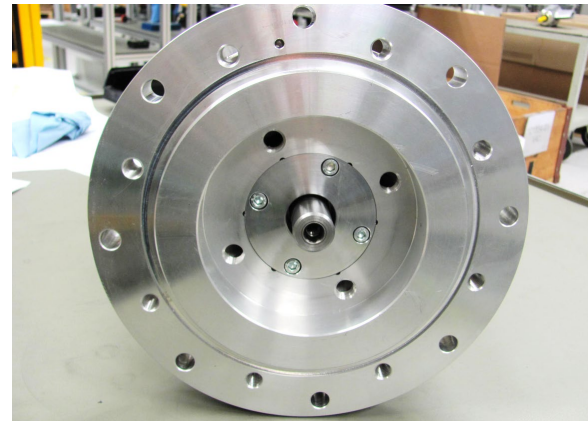
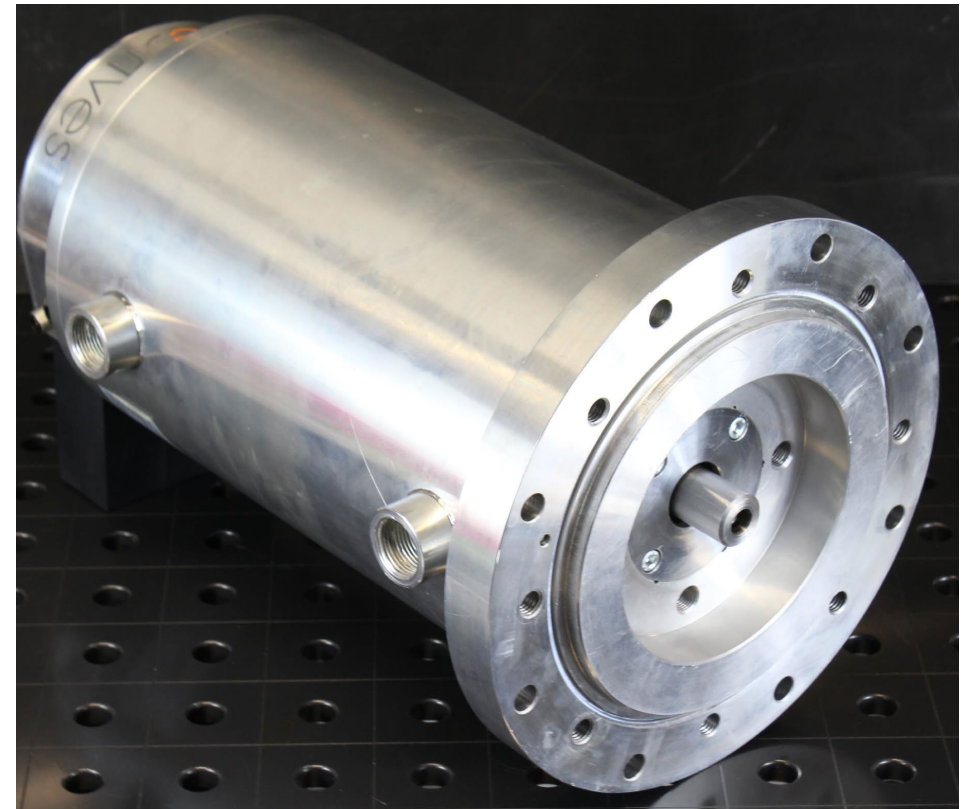
- R1: mechanical tolerances; if taken into account as measured, difference is 188 A vs. 200 A
- R2: to be verified: heat influence zone from laser cutting process



# WP4: Motor-/Generator Design



✓ The demonstrator was finished in November 2021





# WP 7: Development of Power Electronics and System



- After demo facility planning was done, the control cabinet, containing frequency inverter, power feedback unit, filters, fuses, capacitor cabinet, and water and air cooling of the components was finished.
- The pictures show the control cabinet made ready for transport to TU Graz.
- Currently undergoing lab testing